

General linear System

From last class: We considered the complex

$$\begin{cases} x + 3y + 2z - u = a \\ 2x + 6y + z + 4u + 3v = b \\ -x - 3y - 3z + 3u + v = c \\ 3x + 9y + 8z - 7u + 2v = d \end{cases}$$

We defined the augmented matrix

$$M = (A|b) = \left(\begin{array}{cccc|c} 1 & 3 & 2 & -1 & 0 & a \\ 2 & 6 & 1 & 4 & 3 & b \\ -1 & -3 & -3 & 3 & 1 & c \\ 3 & 9 & 8 & -7 & 2 & d \end{array} \right) \rightarrow \left(\begin{array}{cccc|c} \boxed{1} & 3 & 2 & -1 & 0 & a \\ 0 & 0 & \boxed{-3} & 6 & 3 & b-2a \\ 0 & 0 & 0 & 0 & \boxed{4} & d+\frac{2}{3}b-\frac{13}{3}a \\ 0 & 0 & 0 & 0 & 0 & c-\frac{1}{3}b+\frac{5}{3}a \end{array} \right)$$

$$\Rightarrow \text{rank}(A) = 3.$$

We can write the equivalent system:

$$\Rightarrow \begin{cases} x + 3y + 2z - u = a \\ -3z + 6u + 3v = b - 2a \\ 4v = d + \frac{2}{3}b - \frac{13}{3}a \\ 0 = c - \frac{1}{3}b + \frac{5}{3}a \end{cases}$$

To have solutions, we need a compatibility condition

$$\boxed{0 = c - \frac{1}{3}b + \frac{5}{3}a}$$

(2)

otherwise the system has no solution!

$$0 \neq c - \frac{1}{3}b + \frac{5}{3}a \Rightarrow \text{no solution!}$$

Consider $a=0, b=3, c=1$ and $d=1$.

$$\text{Comp. condition } 0 = 1 - \frac{1}{3} \cdot 3 + \frac{5}{3} \cdot 0 = 0 \checkmark$$

Solve linear system:

$$\rightarrow 4v = 3 \Rightarrow |v = 3/4|$$

$$\rightarrow -3z = 3 - 6u - 3v \Rightarrow z = -1 + 2u - v$$
$$= -1/4 + 2u$$

$$|z = -1/4 + 2u|$$

$$\rightarrow x = -3y - 2z + u$$
$$= -3y - 2(-1/4 + 2u) + u$$
$$|x = -3y + 1/2 - 3u|$$

We call y and u free variables: variables corresponding to the columns without a pivot

We call x, z, v basic variables: variables corresponding to the columns with pivot.

Solution to linear system

$$\vec{x} = \begin{pmatrix} 1/2 \\ 0 \\ -1/4 \\ 0 \\ 3/4 \end{pmatrix} + \begin{pmatrix} -3 \\ 1 \\ 0 \\ 0 \\ 0 \end{pmatrix} y + \begin{pmatrix} -3 \\ 0 \\ 0 \\ 1 \\ 0 \end{pmatrix} u, y, u \in \mathbb{R}$$

\Rightarrow we have ∞ solutions!

③

THM (Solution of linear systems) A system $A\underline{x} = \underline{b}$ of m linear equations in n unknowns has either

i) exactly one solution: for instance when $m = n$ and A is nonsingular (invertible).

ii) infinitely many solutions: compatibility condition ✓

iii) no solution (compatibility condition) or not satisfied.

§ Vector spaces and bases

Vector space \rightarrow abstraction of the euclidean space \mathbb{R}^n .

Def (Vector space). A vector space is a set V equipped with two operations $+$ (addition) and \cdot multiplication by scalars s.t.

$$\text{given } \underline{u}, \underline{v} \in V \Rightarrow \underline{u} + \underline{v} \in V$$

$$\text{given } \alpha \in \mathbb{R} \text{ and } \underline{v} \in V \Rightarrow \alpha \cdot \underline{v} \in V$$

and, for all $\underline{u}, \underline{v}, \underline{w} \in V$ and $\alpha, \beta \in \mathbb{R}$ we have

(a) $\underline{u} + \underline{v} = \underline{v} + \underline{u}$ (Commutativity of Addition)

(b) $\underline{u} + (\underline{v} + \underline{w}) = (\underline{u} + \underline{v}) + \underline{w}$ (Associativity of Addition)

(c) $\exists \underline{0} \in V : \underline{0} + \underline{v} = \underline{v} + \underline{0} = \underline{v}$ (Additive Identity)

(d) For each $\underline{v} \in V$, $\exists -\underline{v} \in V$ and

$$\underline{v} + (-\underline{v}) = -\underline{v} + \underline{v} = \underline{0} \quad (\text{Additive Inverse})$$

- (e) $(\alpha + \beta) \cdot \underline{v} = \alpha \cdot \underline{v} + \beta \cdot \underline{v}$ and $\alpha (\underline{v} + \underline{w}) = \alpha \underline{v} + \alpha \underline{w}$ (Distributivity)
- (f) $\alpha (\beta \underline{v}) = (\alpha \beta) \underline{v}$ (Associativity)
- (g) $\exists 1 \in \mathbb{R}$ s.t. $1 \cdot \underline{v} = \underline{v}$. (Identity element)

Examples.

1) \mathbb{R}^m is a vector space

$+$: $\mathbb{R}^m \times \mathbb{R}^m \rightarrow \mathbb{R}^m$

$(\underline{u}, \underline{v}) \mapsto \underline{u} + \underline{v} = \begin{pmatrix} u_1 + v_1 \\ \vdots \\ u_m + v_m \end{pmatrix} \in \mathbb{R}^m$

\cdot : $\mathbb{R} \times \mathbb{R}^m \rightarrow \mathbb{R}^m$

$(\alpha, \underline{u}) \mapsto \alpha \underline{u} = \begin{pmatrix} \alpha u_1 \\ \vdots \\ \alpha u_m \end{pmatrix} \in \mathbb{R}^m$

$\underline{0} = (0, \dots, 0) \in \mathbb{R}^m$

2) $\mathbb{R}^{m \times m}$: Space of matrices with m rows and m columns is a vector space.

3) $\mathbb{P}_m = \{ p(x) : p(x) \text{ is a polynomial and } \deg(p(x)) \leq m \}$

$p(x) = a_0 + a_1 x^1 + \dots + a_m x^m$

$$+ : \mathbb{P}_m \times \mathbb{P}_m \rightarrow \mathbb{P}_m$$

$$(p, q) \mapsto p(x) + q(x)$$

⑤

$$\deg(p+q) \leq m$$

$$\cdot : \mathbb{R} \times \mathbb{P}_m \rightarrow \mathbb{P}_m$$

$$(\alpha, p) \mapsto \alpha p$$

$$\deg(\alpha p) \leq m$$

4) $V = \{ p(x) : p(x) \text{ is a polynomial and } \deg(p(x)) = m \}$

Is V a vector space?

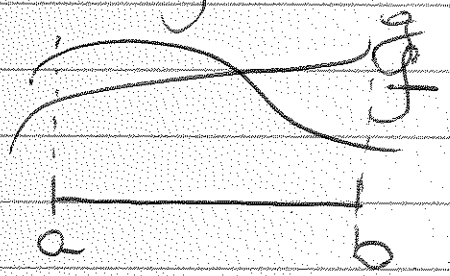
NO:

Counterexample
 $m=2$

$$\begin{aligned} p(x) &= x^2 + 1; & q(x) &= -x^2 + x + 1 \\ \Rightarrow p(x) + q(x) &= x + 1 \notin V & \text{because} \\ \deg(p(x) + q(x)) &= 1 \neq 2 \end{aligned}$$

5) $\mathcal{F} = \{ f(x) : f(x) \text{ is a continuous function on } [a, b] \}$

is a vector space



$$+ : \mathcal{F} \times \mathcal{F} \rightarrow \mathcal{F}$$

$$(f, g) \mapsto f+g$$

$$\cdot : \mathbb{R} \times \mathcal{F} \rightarrow \mathcal{F}$$

$$(\alpha, f) \mapsto \alpha f$$