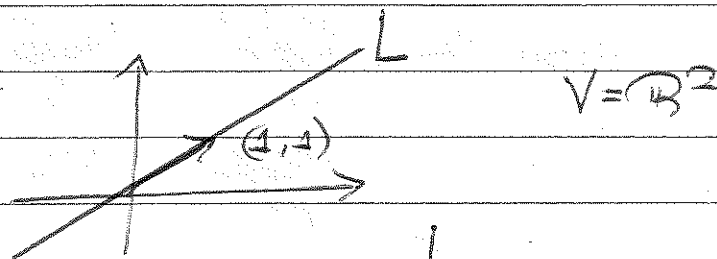


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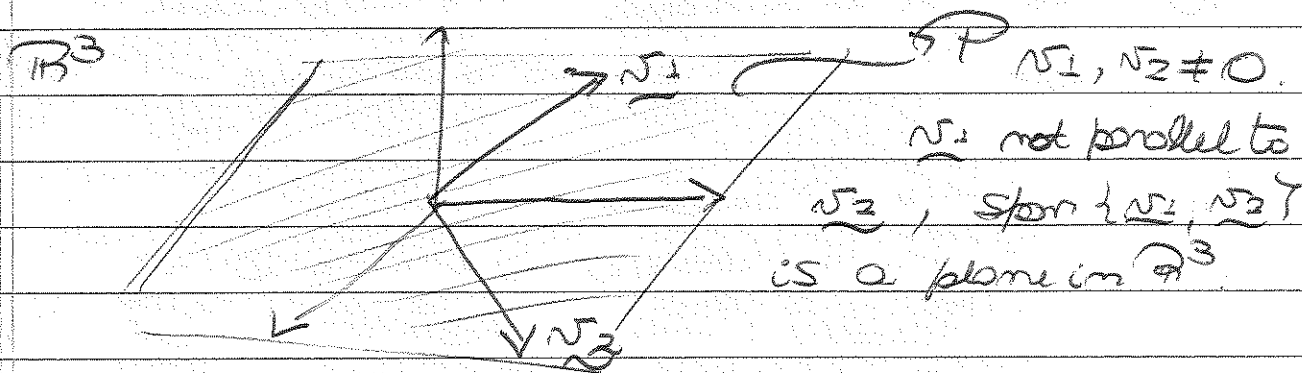
(1)

§2.3 Span and linear independence

Motivation:



$W = \{ \alpha(1,1) ; \alpha \in \mathbb{R} \} =$ line consisting of all vectors parallel to $(1,1) = \text{Span} \{ (1,1) \}$



Definition (Span) Let $\underline{v}_1, \dots, \underline{v}_k \in V$ and V a vector space. A sum of the form

$$c_1 \underline{v}_1 + c_2 \underline{v}_2 + \dots + c_k \underline{v}_k = \sum_{i=1}^k c_i \underline{v}_i$$

where $c_1, c_2, \dots, c_k \in \mathbb{R}$ is known as a linear combination of $\underline{v}_1, \dots, \underline{v}_k$. Their span is $W = \text{Span} \{ \underline{v}_1, \dots, \underline{v}_k \} \subset V$.

Example. $V = \mathbb{R}^3$. If $\underline{v}_1 \neq 0$, then

1) $\text{Span} \{ \underline{v}_1 \} =$ line of all vectors parallel to \underline{v}_1

2) \underline{v}_1 is not parallel to $\underline{v}_2 \Rightarrow \text{Span} \{ \underline{v}_1, \underline{v}_2 \}$

is a plane in \mathbb{R}^3 . If \underline{v}_1 parallel to $\underline{v}_2 \Rightarrow \text{Span} \{ \underline{v}_1, \underline{v}_2 \} = \text{Span} \{ \underline{v}_1 \} = \text{Span} \{ \underline{v}_2 \}$.

②

3) What is the span of $\{(1, 0, 0), (0, 1, 0), (0, 0, 1)\}$
All possible combination of these elements are

$$x(1, 0, 0) + y(0, 1, 0) + z(0, 0, 1), \quad x, y, z \in \mathbb{R}$$
$$(x, y, z)$$
$$\Rightarrow \text{Span}\{(1, 0, 0), (0, 1, 0), (0, 0, 1)\} = \mathbb{R}^3$$

Prop (Span is a Subspace of V). TN Span
 $W = \text{Span}\{\underline{v}_1, \dots, \underline{v}_k\}$ is a subspace of V .

Proof. (i) $\underline{0} \in W$ because

$$\underline{0} = 0 \cdot \underline{v}_1 + 0 \cdot \underline{v}_2 + \dots + 0 \cdot \underline{v}_k$$

(ii) If $\underline{v}, \underline{w} \in W$ then

$$\underline{v} = \sum_{i=1}^k c_i \underline{v}_i \quad \text{and} \quad \underline{w} = \sum_{i=1}^k d_i \underline{v}_i$$

Consequently

$$\alpha \underline{v} + \underline{w} = \alpha \sum_{i=1}^k c_i \underline{v}_i + \sum_{i=1}^k d_i \underline{v}_i$$
$$= \sum_{i=1}^k (\alpha c_i + d_i) \underline{v}_i$$

$$\Rightarrow \alpha \underline{v} + \underline{w} \in W$$

(i) + (ii) $\Rightarrow W$ is a subspace of V . \square

Examples

(a.) $V = \mathbb{P}_2$ - polynomials of degree ≤ 2

$$\text{Span} \{1, x\} = \{p(x) : \alpha \cdot 1 + \beta \cdot x\}$$

$$= \text{polynomials of degree } \leq 1,$$

and $\text{Span} \{1, x\} = \mathbb{P}_1$ is a subspace of $V = \mathbb{P}_2$

$$\text{Span} \{1, x, x^2\} = \{p(x) : \alpha \cdot 1 + \beta \cdot x + \gamma \cdot x^2\}$$

$$= \mathbb{P}_2 - \text{polynomial of degree } \leq 2$$

$\text{Span} \{1, x, x^2\} = \mathbb{P}_2$ is a subspace of $V = \mathbb{P}_2$

(b) Consider the ODE

$$u'' + 2u' - 3u = 0. \tag{1}$$

Solutions: $\lambda^2 + 2\lambda - 3 = 0.$

$$(\lambda - 1)(\lambda + 3) = 0$$

$$\Rightarrow u(x) = C_1 e^x + C_2 e^{-3x}$$

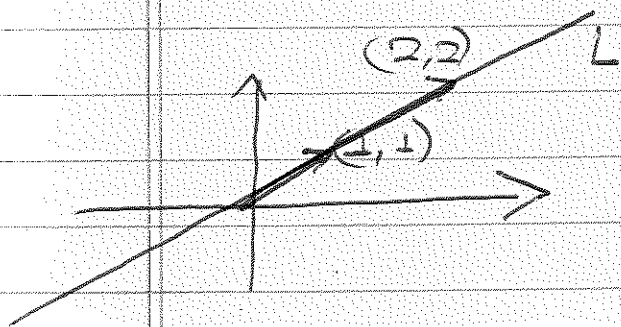
Solution of ODE = $\text{Span} \{e^x, e^{-3x}\}$ □

Linear independence and dependence.

Definition $\mathbb{R}^2 = \text{Span} \{(1, 0), (0, 1)\}$

$$= \text{Span} \{(1, 0), (0, 1), \underbrace{(1, 1)}\}$$

but $(1, 1)$ is redundant.



$$\text{Span} \{(1, 1)\} = L$$

$$\text{Span} \{(2, 2)\} = L$$

$$\text{Span} \{(1, 1), \underbrace{(2, 2)}_{\text{redundant}}\} = L$$

④

Definition (linearly-(in)dependence). The vectors $\underline{v}_1, \dots, \underline{v}_k \in V$ are linearly dependent (l.d) if $\exists c_1, c_2, \dots, c_k$ not all zero s.t.

$$c_1 \underline{v}_1 + \dots + c_k \underline{v}_k = \underline{0}.$$

Vectors $\underline{v}_1, \dots, \underline{v}_k$ are linearly independent (l.i) if

$$c_1 \underline{v}_1 + \dots + c_k \underline{v}_k = \underline{0} \Rightarrow c_1 = c_2 = \dots = c_k = 0.$$

Example.

(a) $V = \mathbb{R}^3$

$$\underline{v}_1 = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix}, \quad \underline{v}_2 = \begin{pmatrix} 0 \\ 3 \\ 1 \end{pmatrix}, \quad \underline{v}_3 = \begin{pmatrix} -1 \\ 4 \\ 3 \end{pmatrix}$$

Notice that

$$\begin{matrix} \boxed{1} \\ \uparrow \end{matrix} \underline{v}_1 - \begin{matrix} \boxed{2} \\ \uparrow \end{matrix} \underline{v}_2 + \begin{matrix} \boxed{1} \\ \uparrow \end{matrix} \underline{v}_3 = \begin{pmatrix} 1 \\ 2 \\ -1 \end{pmatrix} + \begin{pmatrix} 0 \\ -6 \\ -2 \end{pmatrix} + \begin{pmatrix} -1 \\ 4 \\ 3 \end{pmatrix} = \underline{0}$$

$\Rightarrow \{ \underline{v}_1, \underline{v}_2, \underline{v}_3 \}$ is l.d.

(b) Any collection $\{ \underline{v}_1, \dots, \underline{v}_k, \underline{0} \}$ including the vector $\underline{0}$ is l.d. In fact

$$\underline{0} = \begin{matrix} \boxed{1} \\ \uparrow \end{matrix} \underline{0} + 0 \cdot \underline{v}_1 + \dots + 0 \cdot \underline{v}_k$$

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$$(c) V = \mathbb{R}^3$$

$$\underline{v}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}; \quad \underline{v}_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}; \quad \underline{v}_3 = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$c_1 \underline{v}_1 + c_2 \underline{v}_2 + c_3 \underline{v}_3 = \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

if and only if $c_1 = c_2 = c_3 = 0$.

(d) The set

$$1, \cos x, \sin x, \cos^2 x, \cos x \sin x, \sin^2 x$$

is l.d because $\sin^2 x + \cos^2 x = 1$. In fact

$$0 = 1 + 0 \cdot \cos x + 0 \cdot \sin x - 1 \cos^2 x + 0 \cdot \cos x \sin x - 1 \cdot \sin^2 x. \quad \square$$