

## LECTURE 17 | 10/10/14

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Last class review.

Let  $\{\underline{v}_1, \dots, \underline{v}_k\}$  and let  $A = [\underline{v}_1 \ \dots \ \underline{v}_k] \in \mathbb{R}^{m \times k}$ 

Then,

(a)  $\{\underline{v}_1, \dots, \underline{v}_k\}$  are l.d.  $\Leftrightarrow A \underline{c} = \underline{0}$  has a non-zero solution  $\underline{c} \neq \underline{0}$ .

Example.

$$A = \left[ \begin{array}{ccc|c} 1 & 1 & 2 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 2 & 2 & 0 \end{array} \right] \rightarrow \left[ \begin{array}{ccc|c} \boxed{1} & 1 & 2 & 0 \\ 0 & \boxed{1} & 1 & 0 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

$\underline{v}_1 \quad \underline{v}_2 \quad \underline{v}_3$  free variable!

$$\begin{aligned} c_1 + c_2 + c_3 = 0 &\Rightarrow c_2 = -c_3 \\ c_2 + c_3 = 0 &\quad c_1 = -c_2 - c_3 = 0 \end{aligned}$$

Example  $\underline{c} = (0, -1, 1)$  $\Rightarrow \{\underline{v}_1, \underline{v}_2, \underline{v}_3\}$  are l.d.(b)  $\{\underline{v}_1, \dots, \underline{v}_n\}$  are l.i.  $\Leftrightarrow A \underline{c} = \underline{0}$  has the unique solution  $\underline{c} = \underline{0}$ .

Example.

$$A = \left[ \begin{array}{ccc|c} 1 & 1 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 0 \end{array} \right] \Rightarrow \begin{aligned} c_1 + c_2 + c_3 &= 0 \\ c_2 + c_3 &= 0 \\ c_3 &= 0 \end{aligned}$$

$$\Rightarrow c_1 = c_2 = c_3 = 0.$$

$$A = [\underline{v}_1 \dots \underline{v}_k] \in \mathbb{R}^{k \times m}$$

Case  $k > m \Rightarrow \{\underline{v}_1, \dots, \underline{v}_k\}$  is l.d.  
↑  
max columns from nonzeros

Prop. A set of  $k$  vectors in  $\mathbb{R}^m$  is l.i.  $\Leftrightarrow$   
 $A = [\underline{v}_1, \dots, \underline{v}_k] \in \mathbb{R}^{k \times m}$  has  $\text{rank} = m$

Example.  $A = \begin{bmatrix} 1 & 1 & 0 \\ 0 & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix} \rightarrow \begin{bmatrix} \boxed{1} & 1 & 0 \\ 0 & \boxed{1} & 1 \\ 0 & 0 & \boxed{1} \end{bmatrix}$   
 $\underline{v}_1 \quad \underline{v}_2 \quad \underline{v}_3$

$\text{rank } A = 3 \Rightarrow \{\underline{v}_1, \underline{v}_2, \underline{v}_3\}$  is l.i.

### § 2.4 Bases and dimension.

$$V = \mathbb{R}^2 \quad \underline{v}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}; \quad \underline{v}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}; \quad \underline{v}_3 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\text{Span}\{\underline{v}_1, \underline{v}_2\} = \mathbb{R}^2$$

$$\text{Span}\{\underline{v}_1, \underline{v}_2, \underline{v}_3\} = \mathbb{R}^2$$

$$\text{Span}\{\underline{v}_1, \underline{v}_2\} = \left\{ \alpha \cdot (1, 0)^T + \beta (0, 1)^T = (\alpha, \beta)^T \right\} = \mathbb{R}^2$$

$$\begin{aligned} \text{Span}\{\underline{v}_1, \underline{v}_2, \underline{v}_3\} &= \left\{ \alpha (1, 0)^T + \beta (0, 1)^T + \gamma (1, 1)^T \right\} \\ &= \left\{ (\alpha + \gamma, \beta + \gamma)^T \right\} = \mathbb{R}^2 \end{aligned}$$

$$\text{Span}\{\underline{v}_1\} = \left\{ \alpha \underline{v}_1, \alpha \in \mathbb{R} \right\}$$

Definition (basis). A basis of a vector space  $V$  is a finite collection of elements  $\{v_1, \dots, v_m\} \in V$  s.t.

(a)  $\text{Span}\{v_1, \dots, v_m\} = V$

(b)  $\{v_1, \dots, v_m\}$  is l.i.

Examples.

1)  $V = \mathbb{R}^m$  and  $e_1 = \begin{pmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}; e_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ \vdots \\ 0 \end{pmatrix}; \dots; e_m = \begin{pmatrix} 0 \\ \vdots \\ 0 \\ 1 \end{pmatrix}$

$\text{Span}\{e_1, \dots, e_m\} = \mathbb{R}^m$

$\{e_1, e_2, \dots, e_m\}$  is l.i.

$\Rightarrow \{e_1, \dots, e_m\}$  is a basis of  $V = \mathbb{R}^m$ .

2)  $V = \mathbb{P}_2 =$  polynomials of degree 2.

$p_1(x) = 1, p_2(x) = x, p_3(x) = x^2$

$\text{Span}\{p_1(x), p_2(x), p_3(x)\} = \mathbb{P}_2$

$\{p_1(x), p_2(x), p_3(x)\}$  is l.i.

$\Rightarrow \{p_1(x), p_2(x), p_3(x)\}$  is a basis for  $V = \mathbb{P}_2$ .

3)  $V = \mathbb{R}^{2 \times 2}$

$A_1 = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}; A_2 = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}; A_3 = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}; A_4 = \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$

$\text{Span}\{A_1, A_2, A_3, A_4\} = \mathbb{R}^{2 \times 2}$

$\{A_1, A_2, A_3, A_4\}$  is l.i.

$\Rightarrow \{A_1, A_2, A_3, A_4\}$  is a basis of  $V = \mathbb{R}^{2 \times 2}$ .

THM. Every basis of  $\mathbb{R}^m$  consists of exactly  $m$  vectors. In addition,  $\{v_1, \dots, v_m\}$  is a basis if and only if

$$A = [v_1 \dots v_m]$$

- has rank =  $m \iff A$  is nonsingular
- $\iff A$  is invertible
- $\iff \det A \neq 0$ .

Suppose a vector space  $V$  has a basis  $\{v_1, \dots, v_m\}$ . Then every other basis of  $V$  has the same number of elements in it. This number is called the dimension of the space:

$$\dim V = m$$

- Examples
- (a)  $\dim \mathbb{R}^m = m$ .
  - (b)  $\dim \mathbb{P}^2 = 3$ .
  - (c)  $\dim \mathbb{R}^{2+2} = 4$ .

Summary.  $V$  is a  $m$ -dimensional vector space ( $\dim V = m$ ). Then

(a) Every set of more than  $m$  elements of  $V$  is l.d.

Example  $V = \mathbb{R}^3$  the set  $\{v_1, v_2, v_3, v_4\}$  where

$$v_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}; v_2 = \begin{pmatrix} 1 \\ 0 \\ 1 \end{pmatrix}; v_3 = \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}; v_4 = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

is l.d.

(5)

(b) No set of less than  $n$  elements spans  $V$ 

Example:  $V = \mathbb{R}^3$ ;  $\text{Span} \left\{ \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix} \right\} \neq \mathbb{R}^3$

(c) A set of  $n$  elements form a basis  $\Leftrightarrow$  it spans  $V$ .(d) A set of  $n$  elements forms a basis  $\Leftrightarrow$  it is l.i.

Example  $V = \mathbb{R}^{2 \times 2}$

$$W = \{ A \in \mathbb{R}^{2 \times 2} : A = A^T \}$$

Find a basis for  $W$  and its dimension

Solution:  $A = A^T \Leftrightarrow A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} = \begin{pmatrix} a & c \\ b & d \end{pmatrix} = A^T$

$$\Rightarrow A = \begin{pmatrix} a & b \\ b & d \end{pmatrix}$$

$$W = \left\{ A \in \mathbb{R}^{2 \times 2} : A = \begin{pmatrix} a & b \\ b & d \end{pmatrix} \right\}$$

$$= \left\{ A \in \mathbb{R}^{2 \times 2} : A = a \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + b \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + d \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$$

$$= \text{Span} \left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$$

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This set is l.i. In fact

$$\alpha \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} + \beta \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} + \gamma \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$$\Rightarrow \begin{pmatrix} \alpha & \beta \\ \beta & \alpha \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix} \Rightarrow \alpha = \beta = \gamma = 0.$$

Then  $\left\{ \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}, \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix} \right\}$  is a basis for  $V$

and  $\dim W = 3$ .  $\square$