

LECTURE 35. 12/01/14.

Last class review.

§5. Orthogonality.

§5.1 Orthogonal basis. V -vector space, $\langle \cdot, \cdot \rangle$ -inner prod.

Recall that two elements $\underline{u}, \underline{v} \in V$ are orthogonal if $\langle \underline{u}, \underline{v} \rangle = 0$

Def. A basis $\{ \underline{u}_i \}_{i=1}^m$ of V is called orthogonal if $\langle \underline{u}_i, \underline{u}_j \rangle = 0 \forall i \neq j, i, j \in \{1, \dots, m\}$.

The basis is called orthonormal if, in addition, $\| \underline{u}_i \| = 1 \forall i \in \{1, \dots, m\}$.

Example: $V = \mathbb{P}_2$ and $\langle p, q \rangle = \int_0^1 p(x)q(x)dx$.

Then, $\{ 1, x - 1/2, x^2 - x + 1/6 \}$

is an orthonormal basis for \mathbb{P}_2 .

What are the advantages of orthogonal and orthonormal basis? V -vector space, $\langle \cdot, \cdot \rangle$ inner product on V .

If $\{ \underline{v}_1, \dots, \underline{v}_m \}$ is a basis of V , then

$$V \ni \underline{v} = \alpha_1 \underline{v}_1 + \alpha_2 \underline{v}_2 + \dots + \alpha_m \underline{v}_m.$$

How do we find the coefficients $\alpha_i, i=1, \dots, m$?

(2)

In general, we need to solve a linear system. But, if $\{\underline{v}_1, \dots, \underline{v}_m\}$ is orthonormal, then

$$\alpha_i = \langle \underline{v}, \underline{v}_i \rangle, \quad i = 1, \dots, m$$

If $\{\underline{v}_1, \dots, \underline{v}_m\}$ is orthogonal, then

$$\alpha_i = \frac{\langle \underline{v}, \underline{v}_i \rangle}{\|\underline{v}_i\|^2}, \quad i = 1, \dots, m.$$

§ 5.2 Gram-Schmidt process.

How ^{can} we construct an orthogonal/orthonormal basis?

V - finite dimensional vector space; $\dim V = m$ and $\langle \cdot, \cdot \rangle$ - inner product on V . Let's consider

$$\{\underline{w}_1, \dots, \underline{w}_m\}$$

to be a basis of V .

Good. Construct an orthogonal basis $\{\underline{v}_1, \dots, \underline{v}_m\}$

Key idea: $\text{span}\{\underline{w}_i\}_{i=1}^k = \text{span}\{\underline{v}_i\}_{i=1}^k \quad \forall k \in \{1, \dots, m\}$.

Step 1: Take $\underline{v}_1 = \underline{w}_1$.

Step 2: Construct $\underline{v}_2 = \underline{w}_2 - \alpha \underline{v}_1$ s.t.
 $\langle \underline{v}_2, \underline{v}_1 \rangle = 0$.

Now,

$$0 = \langle \underline{v}_2, \underline{v}_1 \rangle = \langle \underline{w}_2 - \alpha \underline{v}_1, \underline{v}_1 \rangle = \langle \underline{w}_2, \underline{v}_1 \rangle - \alpha \langle \underline{v}_1, \underline{v}_1 \rangle \\ \Rightarrow \alpha = \frac{\langle \underline{w}_2, \underline{v}_1 \rangle}{\|\underline{v}_1\|^2}$$

Then, $\underline{v}_2 = \underline{w}_2 - \frac{\langle \underline{w}_2, \underline{v}_1 \rangle}{\|\underline{v}_1\|^2} \underline{v}_1$.

Note that $\underline{v}_2 \neq 0$ since $\{\underline{v}_1, \underline{v}_2\}$ is l.i. \underline{w}_2

Step 3: $\underline{v}_3 = \underline{w}_3 - \alpha_1 \underline{v}_1 - \alpha_2 \underline{v}_2$ s.t.
 $\langle \underline{v}_3, \underline{v}_1 \rangle = 0$ and $\langle \underline{v}_3, \underline{v}_2 \rangle = 0$

$$0 = \langle \underline{v}_3, \underline{v}_1 \rangle = \langle \underline{w}_3, \underline{v}_1 \rangle - \alpha_1 \|\underline{v}_1\|^2 - \alpha_2 \langle \underline{v}_2, \underline{v}_1 \rangle$$
$$\Rightarrow \alpha_1 = \frac{\langle \underline{w}_3, \underline{v}_1 \rangle}{\|\underline{v}_1\|^2}$$

$$0 = \langle \underline{v}_3, \underline{v}_2 \rangle = \langle \underline{w}_3, \underline{v}_2 \rangle - \alpha_2 \|\underline{v}_2\|^2 - \alpha_1 \langle \underline{v}_1, \underline{v}_2 \rangle$$
$$\Rightarrow \alpha_2 = \frac{\langle \underline{w}_3, \underline{v}_2 \rangle}{\|\underline{v}_2\|^2}$$

$$\Rightarrow \underline{v}_3 = \underline{w}_3 - \frac{\langle \underline{w}_3, \underline{v}_1 \rangle}{\|\underline{v}_1\|^2} \underline{v}_1 - \frac{\langle \underline{w}_3, \underline{v}_2 \rangle}{\|\underline{v}_2\|^2} \underline{v}_2$$

Step k : Compute $\underline{v}_k = \underline{w}_k - \sum_{i=1}^{k-1} \alpha_i \underline{v}_i$. What are the values of α_i ?

Imposing orthogonality, we derive

$$0 = \langle \underline{v}_k, \underline{v}_j \rangle = \langle \underline{w}_k, \underline{v}_j \rangle - \alpha_j \|\underline{v}_j\|^2$$
$$\Rightarrow \alpha_j = \frac{\langle \underline{w}_k, \underline{v}_j \rangle}{\|\underline{v}_j\|^2}, \quad j = 1, \dots, k-1.$$

Thus, we have the Gram-Schmidt formula.

$$\underline{v}_k = \underline{w}_k - \sum_{j=1}^{k-1} \frac{\langle \underline{w}_k, \underline{v}_j \rangle}{\|\underline{v}_j\|^2} \underline{v}_j, \quad k = 1, \dots, m.$$

Remark. Gram-Schmidt process defines an orthogonal basis.

To derive an orthonormal basis, we define

$$u_k = \frac{v_k}{\|v_k\|}, \quad k=1, \dots, m.$$

Example: Compute an orthogonal basis $\{q_1, q_2, q_3\}$ of \mathbb{P}_2 with respect to

$$\langle p, q \rangle = \int_0^1 p(x)q(x) dx.$$

Solution: We consider a basis of \mathbb{P}_2 : $\{1, x, x^2\}$.

Now, we compute $\{q_1, q_2, q_3\}$ as follows

1. $q_1 = 1.$

2. $q_2 = x - \alpha q_1$, where $\alpha = \frac{\langle x, 1 \rangle}{\|1\|^2}$

Now, $\langle x, 1 \rangle = \int_0^1 x dx = \frac{1}{2}$, $\|1\|^2 = \int_0^1 dx = 1$

$$\Rightarrow \alpha = 1/2$$

$$\Rightarrow q_2 = x - 1/2.$$

3. $q_3 = x^2 - \alpha \cdot 1 - \beta(x - 1/2)$, where

$$\alpha = \frac{\langle x^2, 1 \rangle}{\|1\|^2}; \quad \beta = \frac{\langle x^2, x - 1/2 \rangle}{\|x - 1/2\|^2}$$

Now, $\langle x^2, 1 \rangle = \int_0^1 x^2 dx = \frac{1}{3}$; $\langle x^2, x - 1/2 \rangle = \int_0^1 x^2(x - 1/2) dx = \frac{1}{12}$

$$\|x - 1/2\|^2 = \int_0^1 (x - 1/2)^2 dx = \frac{1}{12}$$

$$\Rightarrow q_3 = x^2 - 1/3 \cdot 1 - (x - 1/2) = x^2 - x + 1/6. \quad \square$$

§ 5.5. Orthogonal matrices.

Def. A matrix $Q \in \mathbb{R}^{m \times m}$ is orthogonal if
 $Q Q^T = Q^T Q = I_m$.

Properties.

1. $Q^{-1} = Q^T$

2. $Q = [q_1 \ q_2 \ \dots \ q_m]$; $Q^T = \begin{bmatrix} q_1^T \\ q_2^T \\ \vdots \\ q_m^T \end{bmatrix}$

Then, $Q Q^T = [q_1 \ q_2 \ \dots \ q_m] \begin{bmatrix} q_1^T \\ q_2^T \\ \vdots \\ q_m^T \end{bmatrix} = I_m$

$$\Rightarrow \begin{cases} q_i q_j^T = 0 & \text{for } i \neq j, i, j \in \{1, \dots, m\} \\ q_i q_i^T = 1 & \text{for } i \in \{1, \dots, m\}. \end{cases}$$

$\Rightarrow \{q_i\}_{i=1}^m$ is an orthonormal basis of \mathbb{R}^m .

3. $\|Q \underline{x}\|^2 = \langle Q \underline{x}, Q \underline{x} \rangle = \langle Q^T Q \underline{x}, \underline{x} \rangle$
 $= \langle \underline{x}, \underline{x} \rangle = \|\underline{x}\|^2$

$\Rightarrow \|Q \underline{x}\| = \|\underline{x}\|$.

4. $1 = \det(I_m) = \det(Q Q^T) = \det(Q) \cdot \det(Q^T)$
 $= \det(Q)^2$

$\Rightarrow \det(Q) = \pm 1$.